

NAG C Library Function Document

nag_real_sparse_eigensystem_init (f12aac)

1 Purpose

nag_real_sparse_eigensystem_init (f12aac) is a setup function in a suite of functions consisting of nag_real_sparse_eigensystem_init (f12aac), nag_real_sparse_eigensystem_iter (f12abc), nag_real_sparse_eigensystem_sol (f12acc), nag_real_sparse_eigensystem_option (f12adc) and nag_real_sparse_eigensystem_monit (f12aec). It is used to find some of the eigenvalues (and optionally the corresponding eigenvectors) of a standard or generalized eigenvalue problem defined by real non-symmetric matrices.

The suite of functions is suitable for the solution of large sparse, standard or generalized, non-symmetric eigenproblems where only a few eigenvalues from a selected range of the spectrum are required.

2 Specification

```
#include <nag.h>
#include <nagf12.h>
```

```
void nag_real_sparse_eigensystem_init (Integer n, Integer nev, Integer ncw,
    Integer icomm[], Integer licomm, double comm[], Integer lcomm,
    NagError *fail)
```

3 Description

The suite of functions is designed to calculate some of the eigenvalues, λ , (and optionally the corresponding eigenvectors, x) of a standard eigenvalue problem $Ax = \lambda x$, or of a generalized eigenvalue problem $Ax = \lambda Bx$ of order n , where n is large and the coefficient matrices A and B are sparse, real and non-symmetric. The suite can also be used to find selected eigenvalues/eigenvectors of smaller scale dense, real and non-symmetric problems.

nag_real_sparse_eigensystem_init (f12aac) is a setup function which must be called before nag_real_sparse_eigensystem_iter (f12abc), the reverse communication iterative solver, and before nag_real_sparse_eigensystem_option (f12adc), the options setting function. nag_real_sparse_eigensystem_sol (f12acc), is a post-processing function that must be called following a successful final exit from nag_real_sparse_eigensystem_iter (f12abc), while nag_real_sparse_eigensystem_monit (f12aec) can be used to return additional monitoring information during the computation.

This setup function initializes the communication arrays, sets (to their default values) all options that can be set by you via the option setting function nag_real_sparse_eigensystem_option (f12adc), and checks that the lengths of the communication arrays as passed by you are of sufficient length. For details of the options available and how to set them see Section 10.2 of the document for nag_real_sparse_eigensystem_option (f12adc).

4 References

Lehoucq R B (2001) Implicitly Restarted Arnoldi Methods and Subspace Iteration *SIAM Journal on Matrix Analysis and Applications* **23** 551–562

Lehoucq R B and Scott J A (1996) An evaluation of software for computing eigenvalues of sparse nonsymmetric matrices *Preprint MCS-P547-1195* Argonne National Laboratory

Lehoucq R B and Sorensen D C (1996) Deflation Techniques for an Implicitly Restarted Arnoldi Iteration *SIAM Journal on Matrix Analysis and Applications* **17** 789–821

Lehoucq R B, Sorensen D C and Yang C (1998) *ARPACK Users' Guide: Solution of Large-Scale Eigenvalue Problems with Implicitly Restarted Arnoldi Methods* SIAM, Philadelphia

5 Arguments

- 1: **n** – Integer *Input*
On entry: the order of the matrix *A* (and the order of the matrix *B* for the generalized problem) that defines the eigenvalue problem.
Constraint: **n** > 0.

- 2: **nev** – Integer *Input*
On entry: the number of eigenvalues to be computed.
Constraint: 0 < **nev** < **n** – 1.

- 3: **ncv** – Integer *Input*
On entry: the number of Arnoldi basis vectors to use during the computation.
 At present there is no *a priori* analysis to guide the selection of **ncv** relative to **nev**. However, it is recommended that $\mathbf{ncv} \geq 2 \times \mathbf{nev} + 1$. If many problems of the same type are to be solved, you should experiment with varying **ncv** while keeping **nev** fixed for a given test problem. This will usually decrease the required number of matrix-vector operations but it also increases the work and storage required to maintain the orthogonal basis vectors. The optimal ‘cross-over’ with respect to CPU time is problem dependent and must be determined empirically.
Constraint: $\mathbf{nev} + 1 < \mathbf{ncv} \leq \mathbf{n}$.

- 4: **icomm**[*dim*] – Integer *Communication Array*
Note: the dimension, *dim*, of the array **icomm** must be at least max(1, **licomm**).
On exit: contains data to be communicated to the other functions in the suite.

- 5: **licomm** – Integer *Input*
On entry: the dimension of the array **icomm** as declared in the function from which nag_real_sparse_eigensystem_init (f12aac) is called.
 If **licomm** = –1, a workspace query is assumed and the function only calculates the required dimensions of **icomm** and **comm**, which it returns in **icomm**(1) and **comm**(1) respectively.
Constraint: **licomm** ≥ 140 or **licomm** = –1.

- 6: **comm**[*dim*] – double *Communication Array*
Note: the dimension, *dim*, of the array **comm** must be at least max(1, **licomm**).
On exit: contains data to be communicated to the other functions in the suite.

- 7: **lcomm** – Integer *Input*
On entry: the dimension of the array **comm** as declared in the function from which nag_real_sparse_eigensystem_init (f12aac) is called.
 If **lcomm** = –1, a workspace query is assumed and the function only calculates the required dimensions of **icomm** and **comm**, which it returns in **icomm**(1) and **comm**(1) respectively.
Constraint: $\mathbf{lcomm} \geq 3 \times \mathbf{n} + 3 \times \mathbf{nev} \times \mathbf{ncv} + 6 \times \mathbf{ncv} + 60$ or **lcomm** = –1.

- 8: **fail** – NagError * *Input/Output*
 The NAG error argument (see Section 2.6 of the Essential Introduction).

6 Error Indicators and Warnings

NE_BAD_PARAM

On entry, argument $\langle value \rangle$ had an illegal value.

NE_INT

On entry, $n \leq 0$: $n = \langle value \rangle$.

On entry, $nev \leq 0$: $nev = \langle value \rangle$.

NE_INT_2

The length of the integer array **icomm** is too small **licomm** = $\langle value \rangle$, but must be at least $\langle value \rangle$.

NE_INT_3

On entry, $licomm < 3 \times n + 3 \times nev \times nev + 6 \times nev + 60$ where: **licomm** = $\langle value \rangle$, **n** = $\langle value \rangle$, **nev** = $\langle value \rangle$.

On entry, $nev \leq nev + 1$ or $nev > n$ where: **nev** = $\langle value \rangle$, **nev** = $\langle value \rangle$, **n** = $\langle value \rangle$.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

7 Accuracy

Not applicable.

8 Further Comments

None.

9 Example

The example solves $Ax = \lambda x$ in regular mode, where A is obtained from the standard central difference discretization of the convection-diffusion operator $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \rho \frac{\partial u}{\partial x}$ on the unit square, with zero Dirichlet boundary conditions, where $\rho = 100$.

9.1 Program Text

```
/* nag_real_sparse_eigensystem_init (f12aac) Example Program.
 *
 * Copyright 2005 Numerical Algorithms Group.
 *
 * Mark 8, 2005.
 */

#include <nag.h>
#include <nag_stdlib.h>
#include <nag_string.h>
#include <stdio.h>
#include <nagf12.h>
#include <nagf16.h>
#include <nagx04.h>
static void tv(Integer, double *, double *);
static void av(Integer, double *, double *);

int main(void)
{
    /* Constants */
```

```

Integer licomm=140, imon=0;
/* Scalars */
double sigmai=0, sigmar=0, estnrm;
Integer exit_status, irevcm, j, lcomm, n, nconv, ncv, nev;
Integer niter, nshift, nx;
/* Arrays */
double *comm=0, *eigvr=0, *eigvi=0, *eigest=0;
double *resid=0, *v=0;
Integer *icomm=0;
/* Pointers */
double *mx=0, *x=0, *y=0;
/* Nag types */
NagError fail;

exit_status = 0;
INIT_FAIL(fail);

Vprintf("nag_real_sparse_eigensystem_init (f12aac) Example Program Results"
        "\n");
/* Skip heading in data file. */
Vscanf("%*[\n] ");

/* Read values for nx, nev and cnv from data file. */
Vscanf("%ld%ld%ld*[\n] ", &nx, &nev, &ncv);

/* Allocate memory */
n = nx * nx;
lcomm = 3*n + 3*ncv*ncv + 6*ncv + 60;
if ( !(comm = NAG_ALLOC(lcomm, double)) ||
    !(eigvr = NAG_ALLOC(ncv, double)) ||
    !(eigvi = NAG_ALLOC(ncv, double)) ||
    !(eigest = NAG_ALLOC(ncv, double)) ||
    !(resid = NAG_ALLOC(n, double)) ||
    !(v = NAG_ALLOC(n * ncv, double)) ||
    !(icomm = NAG_ALLOC(licomm, Integer)) )
{
    Vprintf("Allocation failure\n");
    exit_status = -1;
    goto END;
}
/* Initialise communication arrays for problem using
   nag_real_sparse_eigensystem_init (f12aac). */
nag_real_sparse_eigensystem_init(n, nev, ncv, icomm, licomm,
                                comm, lcomm, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf(" Error from nag_real_sparse_eigensystem_init (f12aac).\n%s\n",
            fail.message);
    exit_status = 1;
    goto END;
}
/* Select the required spectrum using
   nag_real_sparse_eigensystem_option (f12adc). */
nag_real_sparse_eigensystem_option("SMALLEST MAG", icomm,
                                   comm, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf(" Error from nag_real_sparse_eigensystem_option (f12adc).\n%s\n",
            fail.message);
    exit_status = 1;
    goto END;
}
irevcm = 0;
REVCOMLOOP:
/* Repeated calls to reverse communication routine
   nag_real_sparse_eigensystem_iter (f12abc). */
nag_real_sparse_eigensystem_iter(&irevcm, resid, v, &x, &y, &mx,
                                &nshift, comm, icomm, &fail);
if (irevcm != 5)
{
    if (irevcm == -1 || irevcm == 1)

```

```

    {
        /* Perform matrix vector multiplication y <--- Op*x */
        av(nx, x, y);
    }
    else if (irevcm == 4 && imon == 1)
    {
        /* If imon=1, get monitoring information using
           nag_real_sparse_eigensystem_monit (f12aec). */
        nag_real_sparse_eigensystem_monit(&niter, &nconv, eigvr,
                                           eigvi, eigest, icomm,
                                           comm);

        /* Compute 2-norm of Ritz estimates using
           nag_dge_norm (f16rac). */
        nag_dge_norm(Nag_ColMajor, Nag_FrobeniusNorm, nev, 1, eigest,
                     nev, &estnrm, &fail);
        Vprintf("Iteration %3ld, ", niter);
        Vprintf(" No. converged = %3ld,", nconv);
        Vprintf(" norm of estimates = %16.8e\n", estnrm);
    }
    goto REVCOMLOOP;
}
if (fail.code == NE_NOERROR)
{
    /* Post-Process using nag_real_sparse_eigensystem_sol
       (f12acc) to compute eigenvalues/vectors. */
    nag_real_sparse_eigensystem_sol(&nconv, eigvr, eigvi, v, sigmar,
                                    sigmai, resid, v, comm, icomm,
                                    &fail);

    Vprintf("\n");
    Vprintf("\n The %4ld Ritz values", nconv);
    Vprintf(" of smallest magnitude are:\n\n");
    for (j = 0; j <= nconv-1; ++j)
    {
        Vprintf("%8ld%5s( %12.4f , %12.4f )\n", j+1, "",
                eigvr[j], eigvi[j]);
    }
}
else
{
    Vprintf(" Error from nag_real_sparse_eigensystem_iter (f12abc).\n%s\n",
            fail.message);
    exit_status = 1;
    goto END;
}
END:
if (comm) NAG_FREE(comm);
if (eigvr) NAG_FREE(eigvr);
if (eigvi) NAG_FREE(eigvi);
if (eigest) NAG_FREE(eigest);
if (resid) NAG_FREE(resid);
if (v) NAG_FREE(v);
if (icomm) NAG_FREE(icomm);
return exit_status;
}

static void av(Integer nx, double *v, double *w)
{
    /* Constants*/
    const double beta = 1.0;
    /* Scalars */
    double nx2;
    Integer j, lo;
    /* Nag types */
    NagError fail;

    /* Function Body */
    INIT_FAIL(fail);
    nx2 = -((double) ((nx + 1) * (nx + 1)));
    tv(nx, v, w);
    nag_daxpby(nx, nx2, &v[nx], 1, beta, w, 1, &fail);
    for (j = 2; j <= nx - 1; ++j)

```

```

    {
        lo = (j - 1) * nx;
        tv(nx, &v[lo], &w[lo]);
        nag_daxpby(nx, nx2, &v[lo-nx], 1, beta, &w[lo], 1, &fail);
        nag_daxpby(nx, nx2, &v[lo+nx], 1, beta, &w[lo], 1, &fail);
    }
    lo = (nx - 1) * nx;
    tv(nx, &v[lo], &w[lo]);
    nag_daxpby(nx, nx2, &v[lo-nx], 1, beta, &w[lo], 1, &fail);
    return;
} /* av */

static void tv(Integer nx, double *x, double *y)
{
    /* Compute the matrix vector multiplication y<---T*x where T is a nx */
    /* by nx tridiagonal matrix with constant diagonals (dd, dl and du). */
    /* Scalars */
    double dd, dl, du, nx1, nx2;
    Integer j;
    /* Function Body */
    nx1 = (double) (nx + 1);
    nx2 = nx1 * nx1;
    dd = nx2 * 4.;
    dl = -nx2 - nx1 * 50.;
    du = -nx2 + nx1 * 50.;
    y[0] = dd * x[0] + du * x[1];
    for (j = 1; j <= nx - 2; ++j)
    {
        y[j] = dl * x[j-1] + dd * x[j] + du * x[j+1];
    }
    y[nx-1] = dl * x[nx-2] + dd * x[nx-1];
    return;
} /* tv */

```

9.2 Program Data

nag_real_sparse_eigensystem_init (f12aac) Example Program Data
 10 10 30 : Values for nx, nev and ncv

9.3 Program Results

nag_real_sparse_eigensystem_init (f12aac) Example Program Results

The 10 Ritz values of smallest magnitude are:

1	(	251.8027	,	152.7109	)
2	(	251.8027	,	-152.7109	)
3	(	280.4166	,	152.7109	)
4	(	280.4166	,	-152.7109	)
5	(	325.5237	,	152.7109	)
6	(	325.5237	,	-152.7109	)
7	(	383.4696	,	152.7109	)
8	(	383.4696	,	-152.7109	)
9	(	449.5598	,	152.7109	)
10	(	449.5598	,	-152.7109	)
